CS4423-W04-Jupyter

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1 CS4423-Networks : Lecture 8 [Final version]

2 Colourings and Computations

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This Jupyter notebook, and PDF and HTML versions, can be found at https://www.niallmadden.ie/2425-CS4423/#Week04

This notebook was written by Niall Madden, adapted from notebooks by Angela Carnevale.

2.1 Modules for this notebook

Today, we'll default to lime-coloured nodes. For more options, see https://xkcd.com/color/rgb/

2.2 Our small affiliation network

We built an affiliation network based on data you provided. The network had two types of nodes: * People (usually referred to as *Actors*) * Programmes (here a programme is an example of a *focus*;

so these nodes are *foci*).

We took a subgraph with just 7 people. The data for that is in a file called CS4423-7.txt.

[2]: !cat CS4423-7.txt

Fionn BB Rhea BB NightAgent Cake? Rory BB Penguin Squid Bear NightAgent Bruno Squid JackA BB Squid Bear Boys NightAgent BCS Sam OMitB Squid Boys Cake? NightAgent Andrew BB Squid BCS

We can easily build a network from this file, and draw it:

```
[3]: G7 = nx.read_adjlist('CS4423-7.txt')
# G7 = nx.read_adjlist('CS4423.txt') # uncomment this line to get the full graph
nx.draw(G7, **opts)
```



Let's check the graphs basic properties:

[4]: print(f"G7 is {G7.order()} nodes and {G7.size()} edges")

```
G7 is 16 nodes and 24 edges
```

Unfortunately, this graph can be a little tricky to work with, unless we change it a little. This is not least because **networkx** does not automatically order the nodes the way we would like. In this example, here is how they are ordered:

```
[5]: print(list(G7.nodes()))
```

['Fionn', 'BB', 'Rhea', 'NightAgent', 'Cake?', 'Rory', 'Penguin', 'Squid', 'Bear', 'Bruno', 'JackA', 'Boys', 'BCS', 'Sam', 'OMitB', 'Andrew']

We can see that Nodes 0, 2, 5, 9, 10, 13 and 15 are the "people" nodes. We could build a permutation matrix from this, but will leave that for another time.

2.3 Bipartite graphs in networkx

Since affiliation networks (and, more generally, bipartite graphs) are so important in Network Theory, **networkx** comes with various tools for working with them.

In fact, networkx comes with sub-module, bipartite for working with these graphs.

For example, it has a tool for verifying that a graph is, indeed, bipartite:

```
[6]: print(f"G7 is bipartite: {nx.bipartite.is_bipartite(G7)}")
K33 = nx.complete_bipartite_graph(3,3)
K5 = nx.complete_graph(5)
print(f"K33 is bipartite: {nx.bipartite.is_bipartite(K33)}")
print(f"K5 is bipartite: {nx.bipartite.is_bipartite(K5)}")
```

G7 is bipartite: True K33 is bipartite: True K5 is bipartite: False

One of the key methods is the **sets** function, which tries to compute the parts of the graph, which it returns as a **tuple**:

```
[7]: top, bottom = nx.bipartite.sets(G7)
print(f"Set 1: {top}")
print(f"Set 2: {bottom}")
```

```
Set 1: {'Rory', 'JackA', 'Sam', 'Bruno', 'Rhea', 'Andrew', 'Fionn'}
Set 2: {'Boys', 'NightAgent', 'OMitB', 'Penguin', 'BB', 'Cake?', 'BCS', 'Bear',
'Squid'}
```

Since we can see that Set 1 represents the people, and Set 2 the programmes, let's give them suitable names:

[8]: Actors = top; Foci = bottom;

2.3.1 Drawing

We can use this information, for example, to compute good positions for drawing the graph:





2.3.2 2-colouring

We'll use this to make the *node colouring* which is a list of colours, corresponding the list of nodes.





2.4 Adjacency Matrices

We know the adjacency matrix A of a bipartite graph G, with respect to a suitable ordering/permutation of the nodes (V_1 first, then V_2), has the form of a 2 × 2-block matrix,

$$A = \left(\begin{array}{cc} 0 & C \\ C^T & 0 \end{array}\right)$$

where the blocks on the diagonal consist entirely of zeros, as there are no edges between nodes belonging to the same part.

However, without the right ordering, we don't see this nice structure..

Let's look at the adjacency matrix for G_7 :

```
[12]: A = nx.adjacency_matrix(G7).toarray()
print(A)
```

Here is one way to get a version of the graph with a "nice" ordering:

```
[13]: H=nx.Graph() # make a new, empty graph
H.add_nodes_from(Actors) # first add ther Actor nodes
#print(H.nodes())
H.add_nodes_from(Foci) # then the Foci nodes
```

Check the order:

[14]: print(H.nodes())

```
['Rory', 'JackA', 'Sam', 'Bruno', 'Rhea', 'Andrew', 'Fionn', 'Boys', 'NightAgent', 'OMitB', 'Penguin', 'BB', 'Cake?', 'BCS', 'Bear', 'Squid']
```

Then copy the edges from G_7

```
[15]: H.add_edges_from(G7.edges())  # Now add the edges
```

Let's check the adjacency matrix for H

```
[16]: A = nx.adjacency_matrix(H).toarray() # matrix for H
print(A)
```


2.4.1 The Biadjacency Matrix

Bipartite graphs have a special matrix representation called the **Biadjacency Matrix**. If $|V_1| = r$ and $|V_2| = s$, then it is a $r \times s$ matrix, B, where $b_{ij} = 1$ if there is an edge between Node i in V_1 and Node j in V_2 .

We can compute it as follows:

```
[17]: B = nx.bipartite.biadjacency_matrix(H, Actors, Foci).toarray()
print(B)
```

```
\begin{bmatrix} \begin{bmatrix} 0 & 1 & 0 & 1 & 1 & 0 & 0 & 1 & 1 \\ \begin{bmatrix} 1 & 1 & 0 & 0 & 1 & 0 & 1 & 1 & 1 \\ \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 1 & 0 & 0 & 1 \\ \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 1 \\ \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 1 \end{bmatrix}
```

2.5 Projections

We learned just a while ago that the adjacency matrix of the projection of a bipartite graph G is related the top-left, or bottom-right, non-zero block of A^2

```
[18]: print(A@A)
```

```
[[5 4 2 1 2 2 1 0 0 0 0 0 0 0 0 0]
[4 6 3 1 2 3 1 0 0 0 0 0 0 0 0 0]
[2 3 5 1 2 1 0 0 0 0 0 0 0 0 0 0 ]
[1 1 1 1 0 1 0 0 0 0 0 0 0 0 0]
[2 2 2 0 3 1 1 0 0 0 0 0 0 0 0 0]
[2 3 1 1 1 3 1 0 0 0 0 0 0 0 0 0]
[1 1 0 0 1 1 1 0 0 0 0 0 0 0 0]
[0 0 0 0 0 0 0 2 2 1 0 1 1 1 1 2]
[0 0 0 0 0 0 0 2 4 1 1 3 2 1 2 3]
[0 0 0 0 0 0 0 1 1 1 0 0 1 0 0 1]
[0 0 0 0 0 0 0 0 1 0 1 1 0 0 1 1]
[0 0 0 0 0 0 0 1 3 0 1 5 1 2 2 3]
[0 0 0 0 0 0 0 1 2 1 0 1 2 0 0 1]
[0 0 0 0 0 0 0 1 1 0 0 2 0 2 1 2]
[0 0 0 0 0 0 0 1 2 0 1 2 0 1 2 2]
[0 0 0 0 0 0 0 2 3 1 1 3 1 2 2 5]]
```

However, we can also get these blocks from the Biadjacency matrix, B. The top left is BB^T , and bottom right is B^TB :

[19]: C = B@B.T
print(C)

[[5 4 2 1 2 2 1]
 [4 6 3 1 2 3 1]
 [2 3 5 1 2 1 0]
 [1 1 1 1 0 1 0]
 [2 2 2 0 3 1 1]
 [2 3 1 1 1 3 1]
 [1 1 0 0 1 1 1]]
However, this is not an adjacency matrix of a (simple) graph:

```
[20]: G7_1 = nx.from_numpy_array(C)
nx.draw(G7_1, **opts)
```



But we can convert it to one:

[21]: C[C>0]=1 # set everything to 0 or 1 np.fill_diagonal(C,0) # Set diagonal entries to 0 print(C) $\begin{bmatrix} \begin{bmatrix} 0 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & 1 & 0 & 1 \\ 1 & 1 & 0 & 0 & 1 & 1 \end{bmatrix}$

[22]: G7_2 = nx.from_numpy_array(C) nx.draw(G7_2, **opts)



We could have used the **networkx** function **projected_graph** (taking input a bipartite graph and one of the two sets of vertices) does this for us:

```
[23]: G_V1 = nx.projected_graph(H, Actors)
nx.draw(G_V1, **opts)
```



Here is the projection on to V_2 .

[24]: G_V2 = nx.projected_graph(H, Foci) nx.draw(G_V2, **opts)



Finished here Thursday